

DOCUMENT TITLE: Operation & Maintenance Manual for Gear Box CI. 7

PROJECT TITLE: 8.3. ISO-6&7-Mech.Interfaces

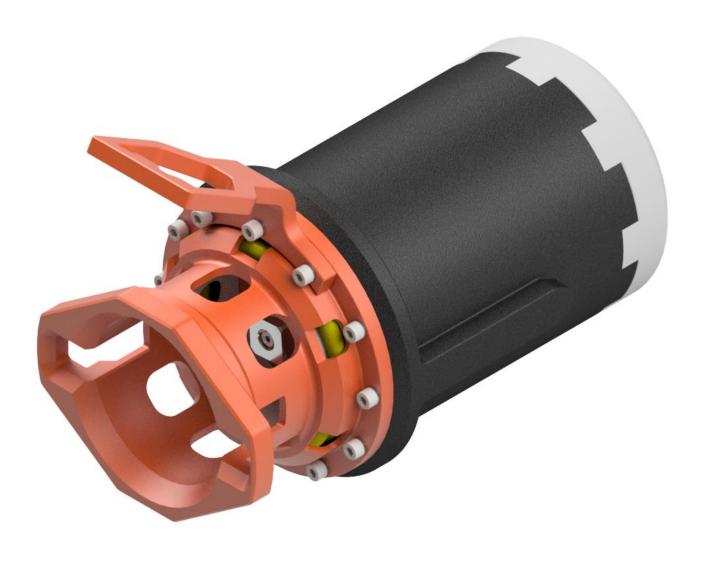
PROJECT: 600146

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DATE: 21.09.2022

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OBJECTIVE

The objective of this document is to present a comprehensive technical description of the Blue Logic Class 7 Gearbox. Relevant technical aspects for information and familiarization are covered as well as detailed technical data. For further information reference is made to drawing BB2408 Gear Box Cl.7

ABSTRACT

The Blue Logic Gear Box CI. 7 is designed in accordance with ISO/API, and the purpose is to enable operation of equipment with Class 7 interface using a torque tool with Class 4 output interface.

REVISION CHANGE/RECORD

REV	REASON FOR REVISION/ DESCRIPTION OF CHANGES	
01	Issued for Use	
02	Added information regarding 10kNm & 15kNm versions	



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TECHNICAL DOCUMENT

1. INTRODUCTION

The Class 7 Gearbox is designed to enable operation of Class 7 and Class 6 interfaces using a Class 4 torque tool for maximum flexibility at minimum cost.

The gearbox can be configured for both short and long Class 7 interface, in addition to Class 6 using a square insert.

The gearbox can be delivered as a complete kit(BB2408), including required components to adapt the tool to the interfaces as described above.

The Gearboxes are delivered as 40kNm(BA6403), 15kNm(BA6847) & 10kNm(BA8497) versions.

1.1. DOCUMENT USE

This document shall be used as a general information for all aspects related to safe use, installation, removal, maintenance, and storage of the Class 7 Gearbox.

1.2. REFERENCES

Latest version of the following documents

ld.	Doc. No	Originator	Document Title
/01/	BB2408	Blue Logic	Gear Box Cl.7 Arrangement
/02/	BA6403	Blue Logic	Class 7 Gear Box 40kNm
/03/	BA6847	Blue Logic	Class 7 Gear Box 15kNm
/04/	BA8497	Blue Logic	Class 7 Gear Box 10kNm
/05/	BB1677	Blue Logic	Class 7 Gear Box 40kNm Long*
/06/	600146-TD-0009	Blue Logic	Assembly and Test Procedure for Class 6&7
			Gearbox

^{*} Dimensions for "long version" are similar for 10kNm & 15kNm

1.3. ABBREVIATIONS

ROV	Remotely Operated Vehicle
HPU	Hydraulic Power Unit
FAT	Factory Acceptance Test
TT	Torque Tool



2. TECHNICAL DESCRIPTION

2.1. GENERAL

The gearbox is designed to be a compact tool with low submerged weight to enable efficient ROV intervention. As base case, the gearbox is intended to be used as a stand-alone unit for installation in Class 7 interfaces. Once installed, the Class 4 torque tool, hereafter referred to as TT, shall be inserted in the Class 4 interface of the gearbox. The unit is then ready for operation.

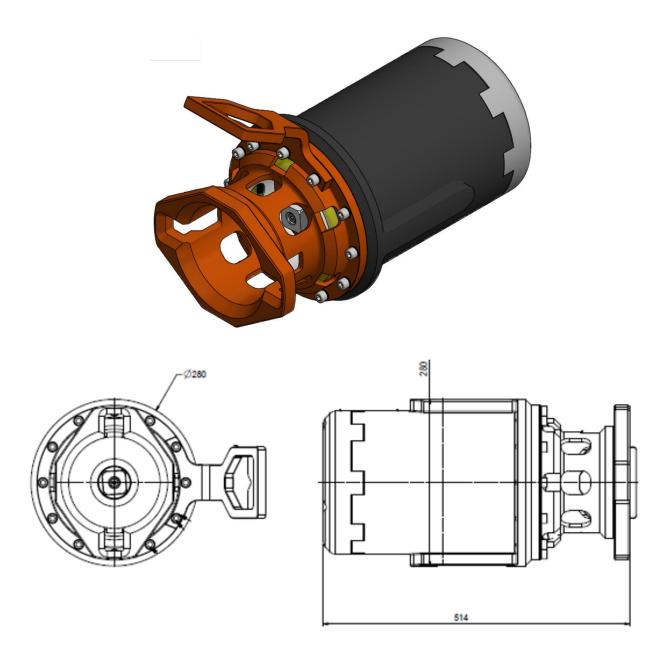


Figure 1, Cl.7 gearbox, short configuration



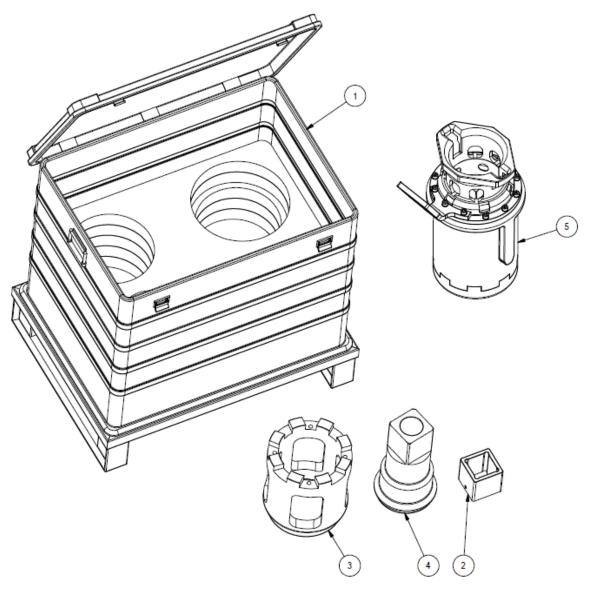


Figure 2 Class 7 gearbox, complete kit (BB2408)

The gearbox can be delivered in a transport box, containing the following main components as shown above: The gearbox can be delivered in 10kNm or 15kNm, with the same accessories.

Item	Description	Reference
1	Transport box	BB3819
2	Insert Class 6	BB1680
3	Protection Nose Class 7 - Long	BB1679
4	Planetary Carrier Class 7 Extension - Long	BB1678
5	Class 7 Gear Box 40kNm - Short	BA6403
6	Operation and Maintenance Manual	600146-TD-0006

TECHNICAL DOCUMENT

2.2. INTERFACES

2.2.1. Mechanical Interface

Torque Input:

- ISO/API Class 4

Torque Output:

- ISO/API Class 7 short
- ISO/API Class 7 long
- ISO/API Class 6

ROV Interface:

- ROV D-handle

2.2.2. Hydraulic Interface

The gearbox is all-mechanical, but the housing is pressure compensated using an oil-filled ½" Tygon compensator hose. Blind fitting at the end of the hose to be pulled out for filling/draining of compensation hose. Make sure to evacuate all air when filling with oil. Gear-oil: Q8 T 65 75W-90.

2.3. MATERIAL SELECTION

The gearbox is mainly constructed in anodized Aluminium, and designed for intervention, i.e. not permanent installation

2.4. TECHNICAL DATA

The below data represents a standard, short, version of the gearbox.

Overall dimensions	Ø280 x 514 mm
Weight in air	71.1 kg
Weight in water	56,94 kg
Pressure rating	300 bar
Max water depth	3 000 m
Max output, gear ratio 1:14,273	40 kNm
Max output, gear ratio 1:6	15 kNm
Max output, gear ratio 1:3,78	10 kNm
Gear-oil	Q8 T 65 75W-90

TECHNICAL DOCUMENT

3. OPERATION

3.1. PREPARATIONS

Prior to operation, the following actions shall be carried out.

ID	Description	
1	Check the gearbox for damages.	
2	Verify correct output interface selected. Replace output interface if required,	
	ref. section 3.4.	
3	Insert the Class 4 TT and operate gearbox to verify smooth and correct	
	operation.	
4	Put the gearbox in vertical position with the Class 4 interface up. Verify that	
	the compensation hose is oil filled. Evacuate any air if present.	

3.2. OPERATION

ID	Description		
1	Grab the gearbox' D-handle and use the manipulator to install the gearbox		
	into the correct Class 7 intervention bucket. The gearbox can be used in both		
	vertical and horizontal orientation. The gearbox is held in position by		
	gravity/friction, thus no locking mechanism to be engaged. Alignment of		
	output socket may be necessary for fully insertion.		
2	Insert the Class 4 TT and slowly operate in required direction in order to align		
	the gearbox' output socket with the Class 7 interface. In vertical orientation,		
	the gearbox will drop into final position once aligned. For horizontal		
	orientation, the ROV must apply a gentle push during the alignment.		
3	Perform intervention as required for the application.		
4	When operation has been completed, remove the Class 4 TT.		
5	Grab the D-handle and pull the gearbox out of the Class 7 interface bucket.		

3.3. PRE-OPERATION

The following actions shall be taken once the gearbox has been recovered to deck.

ID	Description	
1	Hose down the gearbox using fresh water.	
2	Check for damages, special attention to be made to input and output	
	interfaces.	
3	Put the tool in vertical orientation and verify that the compensation hose is	
	completely oil-filled. Refill if required.	
4	Insert the Class 4 TT and operate the gearbox to verify correct and smooth	
	operation.	
5	Wipe off any water and install the gearbox in dedicated transport box.	

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TECHNICAL DOCUMENT

3.4. REPLACEMENT OF OUTPUT INTERFACE

For increased flexibility, the output interface is interchangeable to fit different interfaces;

- Class 7 short
- Class 7 long
- Class 6 short
- Class 6 long

Please follow below instructions for changing between the above listed configurations.

3.4.1. Change from Short to Long Nose

ID	Description	
1	Use an Allen key to release 4 off M10x40 bolts and remove the protection nose.	
2	Insert the extension socket, BB1678, into the main socket.	28
3	Install the extended protection nose, BB1679. Install and tighten all M10x40 bolts, 4 off. Torque: 43Nm	
4		



3.4.2. Installation of Class 6 Insert

The below procedure provides information of how to install the Class 6 insert socket.

ID	Description	
1	Insert the Class 6 insert socket, BB1680, into the Class 7 socket.	
2	Install 2 off M10 set screws and secure the insert to the main socket.	



3.4.3. Installation of GHO adapter

To install the GHO adapter (Art. Nr.: BB5605), follow the instructions below.

	:all the GHU adapter (Art. Nr.: BB56U5), follow Description	the matractions below.
ID 1	Description	
	Use an Allen key to release 4 off M10x40 bolts and remove the protection nose.	28
2	Install the GHO adapter, BB5605, and tighten all M10x40 bolts, 4 off. Torque: 43Nm	
3		



4. MAINTENANCE

4.1. YEARLY MAINTEANCE

ID	Description	
1	Check gearbox for damages, special attention to be made to input and output interfaces.	
2	Check coating, touch-up if required.	
3	Remove the plastic protection plate inside the class 4 bucket and pull out the compensation hose. Remove the endplug from the hose.	
4	Unscrew BSP plug inside the socket. Remove plug inserted in the compensation hose to allow draining. Check oil for contamination, debris, water etc.	28
5	Put the tool in vertical position with the CI7 interface upwards. Connect an oil-pump to the compensation hose and pump oil until it bleeds out of the BSP port. Reinstall the BSP plug.	Gear-oil: Q8 T 65 75W-90
6	Put the gearbox in vertical orientation with the CI4 interface upwards. Check for bubbles of air in compensation hose. Use vacuum pump to evacuate any trapped air and refill oil if required.	
7	Disconnect the oil-pump and reinstall the plug for the compensation hose.	



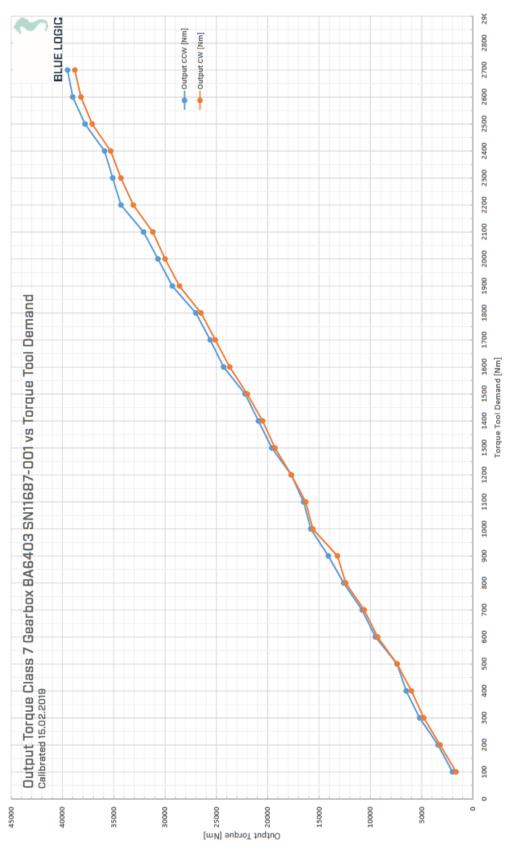
4.3. 2-YEARLY MAINTEANCE

If the gearbox has been in operation for 2 years, it should be returned to Blue Logic for full inspection and maintenance.

ID	Description	
1	Check gearbox for damages, special attention to be made to input and output interfaces.	
2	Check coating, touch-up if required.	
3	Drain all oil through the BSP port. Inspect oil for water, debris etc.	
4	Open gearbox and perform a full inspection of all internal parts, gears etc. Replace parts and seals if required.	
5	Assemble gearbox and fill with oil.	Gear-oil: Q8 T 65 75W-90
6	Perform function test to verify full functionality.	



5. APPENDIX 1 – TORQUE CURVE

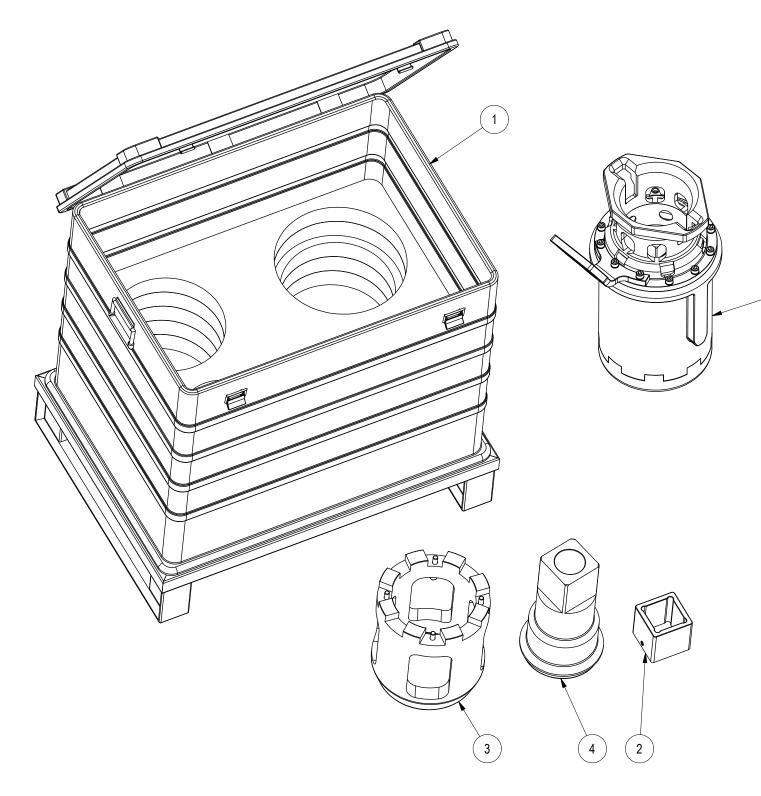




APPENDIX 2 – GEARBOX CL.7 ARRANGEMENT DWG Drawing BB2408

02

	Parts List					
ITEM	QTY	PART No.	TITLE	WEBLINK		
1	1	BB3819	Alu Box Assy for Gear Box Cl. 7	N/A		
2	1	BB1680	Insert Class 6	N/A		
3	1	BB1679	Protection Nose Class 7 Long	N/A		
4	1	BB1678	Plantary Carrier Class 7 Extension Long	N/A		
5	1	BA6403	Class 7 Gear Box 40kNm	http://e-sea.bluelogic.no/main.aspx?page=article&artno=BA6403		



NOTE: 1 DESIGN CODE: ISO 13628-8/API 17H

NOTE: 2

TECHNICAL CLASSIFICATION: Article Type:

008-Actuation 8.03. ISO-6-7 Actuaiton Main Group: Intermediate Group: 8.46.04. Test Jig Sub Group: 8.46.134.02. Intervention

NOTE: 3

INTERFACE INFORMATION: Pressure Rating Bar: 300 Material: 115,7 kg 132,77 dm^3 Weight: Volume: 154062 cm^2 Surface Area:

Hydraulic:

Mechanical: ISO/API 17H Class 4 and Class 7

Electrical: N/A N/A Com. & Protocol:

NOTE: 4

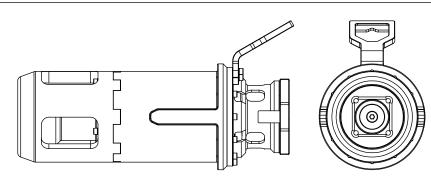
ADDITIONAL INFORMATION:

Mechanical Gear box with ISO Class 4 input and ISO Class 7 output

40kNm torque capacety.

The gearbox can be configured for Class 7 short and long.

A square insert is delivered to also meet Class 6 dimensions. Gear ratio can be either 14.31:1, 6.0:1 or 3.79:1 for maximum flexibility.



BB1677 Class 7 Gear Box 40kNm Long

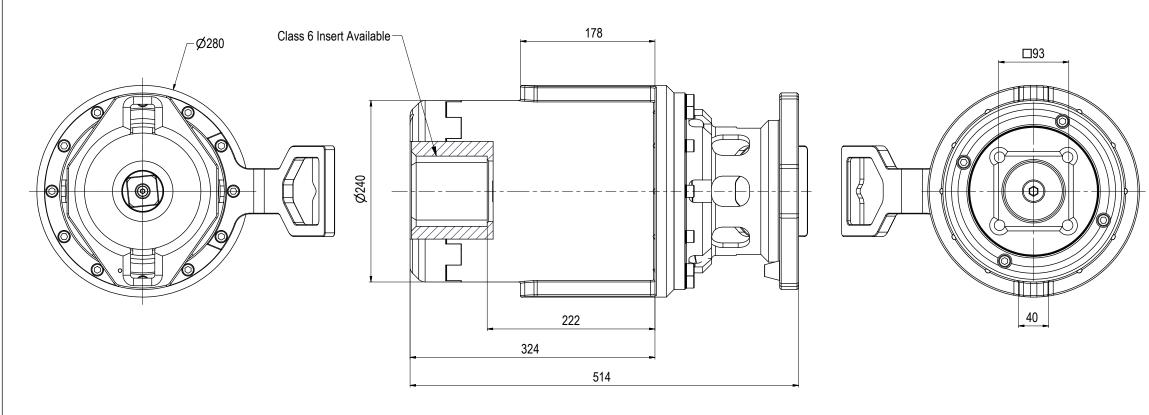
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02	10.9.2019	9-IFU (Issued for Use)		WTJ	LGH	WTJ
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Rev.	Date	Reason for issue	Revision change	Made	Chk'd	Appr.



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Dwg Fo	ormat:		
		Drawing number: BB2408	Rev. 03



7. APPENDIX 3 – CLASS 7 GEARBOX 40KNM SHORT Drawing BA6403





TECHNICAL CLASSIFICATION: Article Type: 008-Actuation 8.03. ISO-6-7 Actuaiton Main Group: Intermediate Group: 8.46.03. Gear

Sub Group: 8.46.128.02. Intervention

NOTE: 3

INTERFACE INFORMATION: Pressure Rating Bar: 300
Design Water Depth: 3000m Material: N/A Weight: 71,1 kg Volume: 13,83 dm^3 Submerged Weight: 56,92 kg 30578 cm² Surface Area:

Hydraulic: N/A

ISO Class 4 Input Mechanical:

N/A Electrical: N/A Com. & Protocol:

NOTE: 4

ADDITIONAL INFORMATION:

API 17H Class 4 to 7 gearbox for short term use / intervention. The gearbox is oil filled and pressure compensated using passive, integrated compensator. Main housing constructed in hard anodized Aluminum, nose section in POM and output socket in S165M.

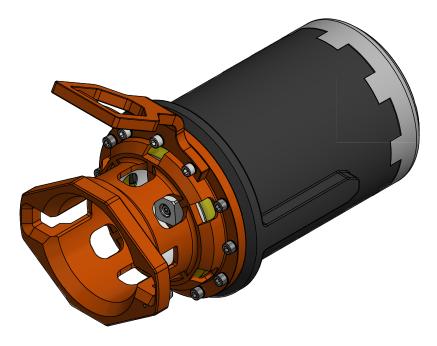
Mechanical Gear box with ISO Class 4 input and ISO Class 7 output. 40kNm torque capacety. Gear Ratio 40kNm 1:14.273

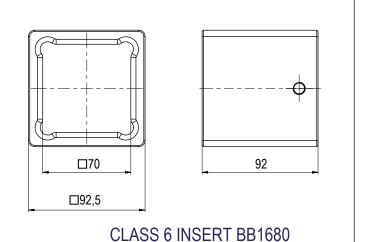
Class 6 Insert available on request, BB1680

Can be configured to 10kNm and 15kNm torque output. Gear Ratio 15kNm 1:6 (ref BA6847)

Gear Ratio 10kNm 1:3,78 (ref BA8497)

Gear Ratio 40kNm Long 1:14.273 (ref BB1677)





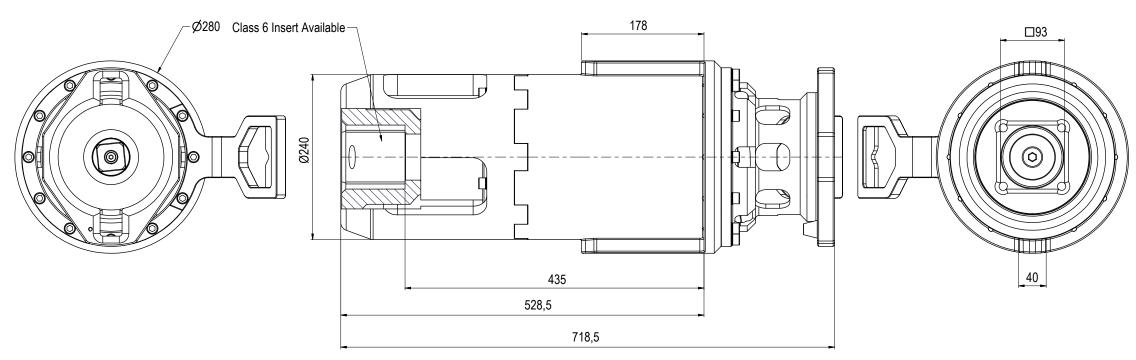
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10	11.2.2022	9-IFU (Issued for Use)			WTJ	KHA	WTJ
09	26.8.2021	9-IFU (Issued for Use)			WTJ	LGH	WTJ
08	16.4.2021	9-IFU (Issued for Use)			WTJ	LGH	WTJ
Rev.	Date	Reason for issue	Revision change		Made	Chk'd	Appr.

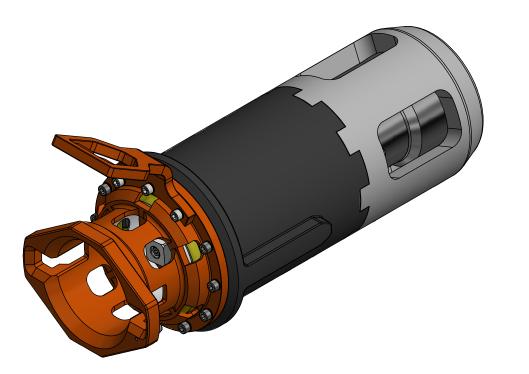


Dwg Scale:	Drawing title:	
NTS	Class 7 Gear Box 40kNm	
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Dwg Format: A3		
A3		
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	IRA6403	



8. APPENDIX 4 - CLASS 7 GEARBOX 40KNM LONG Drawing BB1677





NOTE: 1 DESIGN CODE: API 17H

NOTE: 2

TECHNICAL CLASSIFICATION:
Article Type: 008-Actuation
Main Group: 8.03. ISO-6-7 Actuaiton

Intermediate Group: 8.46.03. Gear

Sub Group: 8.46.128.02. Intervention

NOTE: 3

INTERFACE INFORMATION:
Pressure Rating Bar: 300
Design Water Depth: 3000m
Material: N/A
Weight: 93,9 kg
Volume: 19,46 dm^3
Submerged Weight: 73,95 kg
Surface Area: 36574 cm^2
Hvdraulic: N/A

Mechanical: ISO Class 4 Input Flectrical: N/A

Electrical: N/A Com. & Protocol: N/A

NOTE: 4

ADDITIONAL INFORMATION:

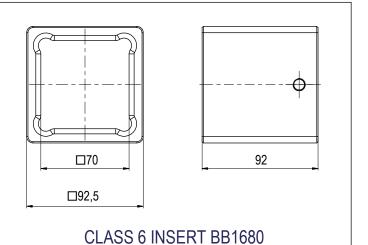
API 17H Class 4 to 7 gearbox short term use / intervention. The gearbox is oil filled and pressure compensated using passive integrated compensator. Main housing constructed in hard anodized Aluminum, nose section in POM and output socket in S165M.

Mechanical Gear box with ISO Class 4 input and ISO Class 7 output. 40kNm torque capacety. Gear Ratio 40kNm 1:14.273

Class 6 Insert available on request, BB1680

Can be configured to 10kNm and 15kNm torque output. Gear Ratio 15kNm 1:6 Gear Ratio 10kNm 1:3,78

Gear Ratio 10kNm Short 1:3,78 (ref BA8497) Gear Ratio 15kNm Short 1:6 (ref BA6847) Gear Ratio 40kNm Short 1:14.273 (ref BA6403)



06	24.8.2022	9-IFU (Issued for Use)		WTJ	LGH	WTJ
05	11.2.2022	9-IFU (Issued for Use)		WTJ	KHA	WTJ
04	7.7.2021	9-IFU (Issued for Use)		WTJ	LGH	WTJ
03	16.10.2019	9-IFU (Issued for Use)		WTJ	LGH	WTJ
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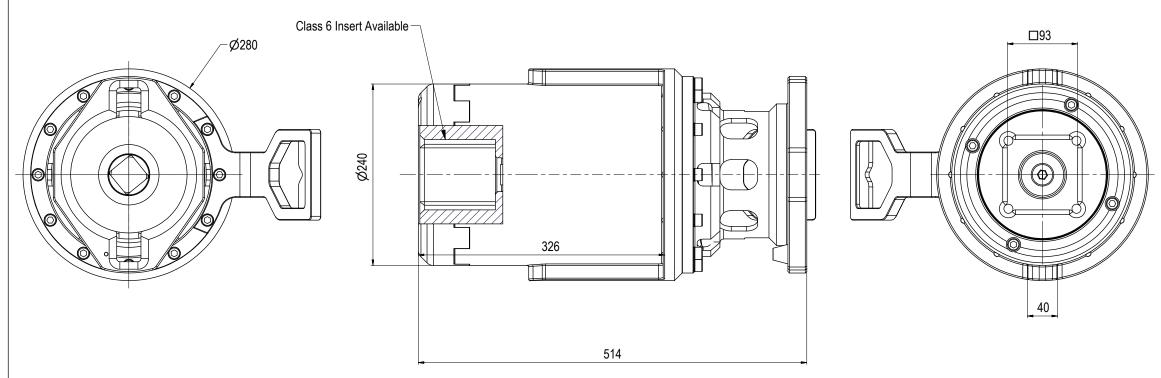


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9. APPENDIX 5 - CLASS 7 GEAR BOX 15KNM

DWG: BA6847



NOTE: 1 DESIGN CODE: API 17H

NOTE: 2

TECHNICAL CLASSIFICATION: Article Type: 008-Actuation 8.03. ISO-6-7 Actuaiton Main Group: Intermediate Group: 8.46.03. Gear

8.46.128.02. Intervention Sub Group:

NOTE: 3

INTERFACE INFORMATION: Pressure Rating Bar: 300 Design Water Depth: 3000m Material: 62,7 kg Weight in Air: Volume: 12,83 dm^3 Submerged Weight: 49,59 kg Surface Area: 26069 cm^2 N/A Hydraulic:

ISO Class 4 Input Mechanical:

N/A Electrical: N/A Com. & Protocol:

NOTE: 4

ADDITIONAL INFORMATION:

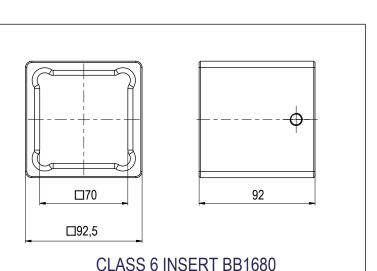
API 17H Class 4 to 7 gearbox for short term use / intervention. The gearbox is oil filled and pressure compensated using passive, integrated compensator. Main housing constructed in hard anodized Aluminum, nose section in POM and output socket in S165M.

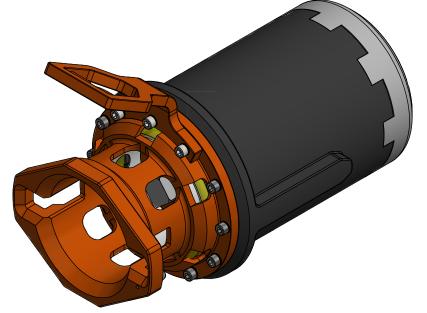
Mechanical Gear box with ISO Class 4 input and ISO Class 7 output. 15kNm torque capacety. Gear Ratio 15kNm 1:6

Can be configured to 10kNm and 40kNm torque output. Gear Ratio 10kNm 1:3,78 (ref BA8497)

Gear Ratio 40kNm 1:14.273 (ref BA6403)

Gear Ratio 40kNm Long 1:14.273 (ref BB1677)





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08	11.2.2022	9-IFU (Issued for Use)		WTJ	KHA	WTJ
07	26.8.2021	9-IFU (Issued for Use)		WTJ	LGH	WTJ
06	19.3.2021	9-IFU (Issued for Use)		WTJ	LGH	WTJ
Rev.	Date	Reason for issue	Revision change	Made	Chk'd	Appr.

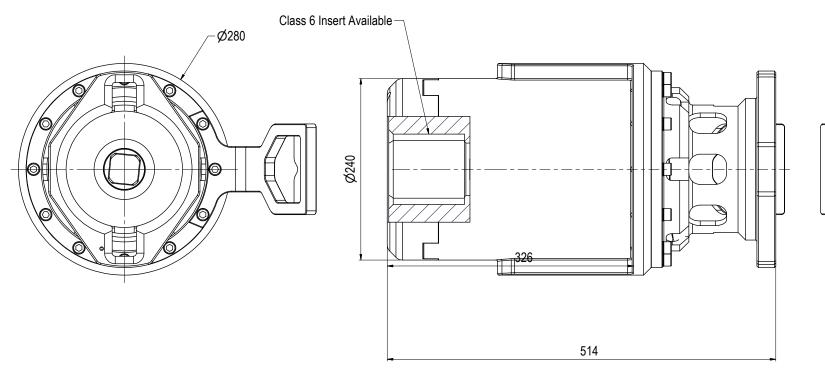
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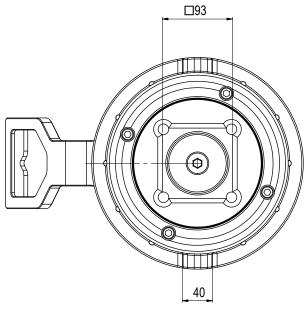
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ITS	—Class 7 Gear Box 15kNm	
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wg Format: 3		
	Drawing number:	Rev.



10. APPENDIX 6 - CLASS 7 GEAR BOX 10KNM

DWG: BA8497





NOTE: 1 **DESIGN CODE:** API 17H

NOTE: 2

TECHNICAL CLASSIFICATION: Article Type: 008-Actuation 8.03. ISO-6-7 Actuaiton Main Group:

Intermediate Group: 8.46.03. Gear

8.46.128.02. Intervention Sub Group:

NOTE: 3

INTERFACE INFORMATION: Pressure Rating Bar: 300 Design Water Depth: 3000m N/A Material: Weight in Air: 61,6 kg 12,68 dm^3 Volume: Submerged Weight: 48,58 kg Surface Area: 26298 cm^2 N/A

Hydraulic:

Mechanical: ISO Class 4 Input N/A

Electrical: N/A Com. & Protocol:

NOTE: 4

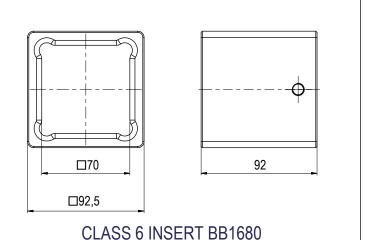
ADDITIONAL INFORMATION:

API 17H Class 4 to 7 gearbox for short term use / intervention. The gearbox is oil filled and pressure compensated using passive, integrated compensator. Main housing constructed in hard anodized Aluminum, nose section in POM and output socket in S165M.

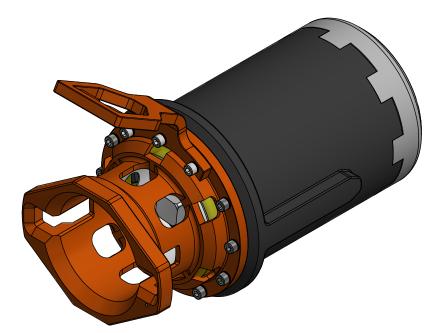
Mechanical Gear box with ISO Class 4 input and ISO Class 7 output. 10kNm torque capacety. Gear Ratio 10kNm 1:3,78

Can be configured to 15kNm and 40kNm torque output. Gear Ratio 15kNm 1:6 (ref BA6847) Gear Ratio 40kNm 1:14.273 (ref BA6403)

Gear Ratio 40kNm Long 1:14.273 (ref BB1677)



05	24.8.2022	9-IFU (Issued for Use)		WTJ	LGH	WTJ
04	11.2.2022	9-IFU (Issued for Use)		WTJ	KHA	WTJ
03	27.10.2021	9-IFU (Issued for Use)		WTJ	LGH	WTJ
02	18.10.2019	9-IFU (Issued for Use)		WTJ	LGH	WTJ
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